

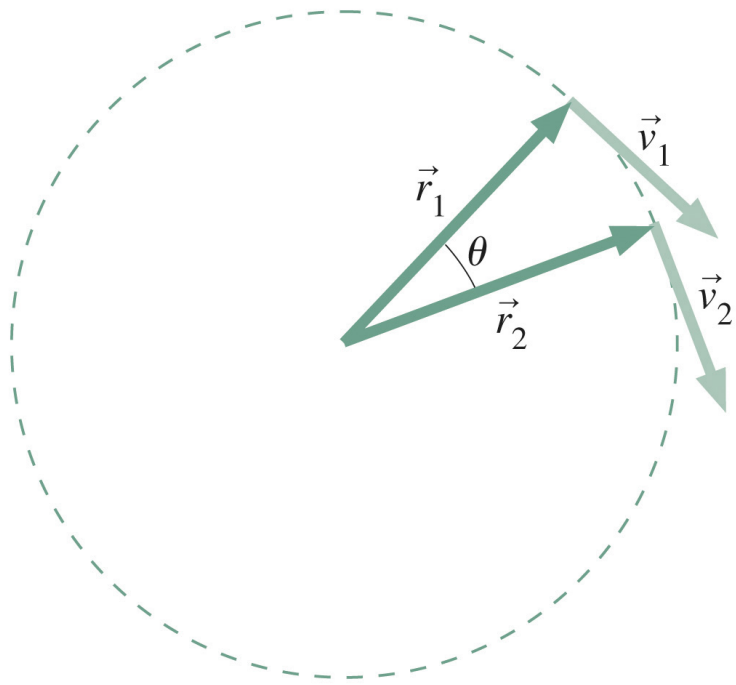
Chapter 6: Work, Energy and Power

Tuesday February 10th

- Finish Newton's laws and circular motion
- Energy
 - Work (definition)
 - Examples of work
- Work and Kinetic Energy
- Conservative and non-conservative forces
- Work and Potential Energy
- Conservation of Energy
- As usual - iclicker, examples and demonstrations

Reading: up to page 88 in the text book (Ch. 6)

Newton's 2nd law and uniform circular motion



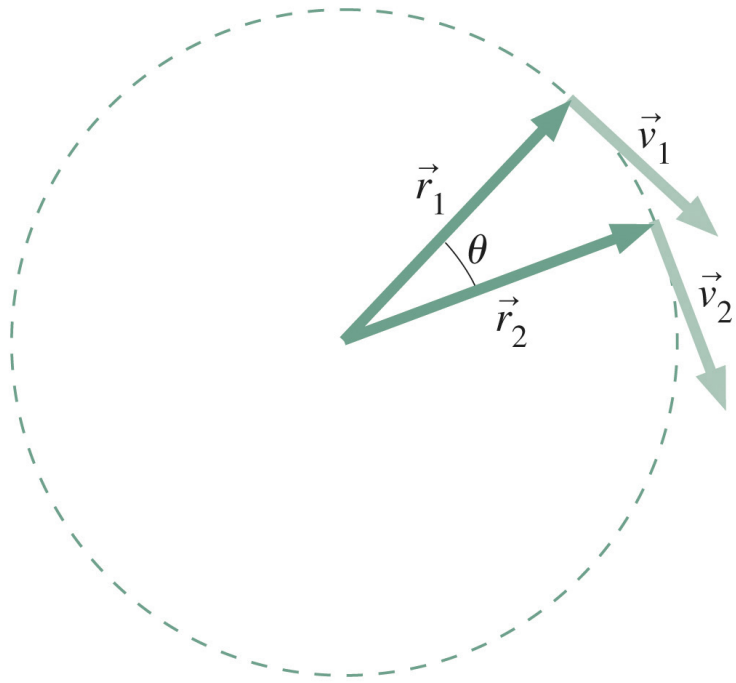
- Although the speed, v , does not change, the direction of the motion does, *i.e.*, the velocity, which is a vector, does change.
- Thus, there is an acceleration associated with the motion.
- We call this a centripetal acceleration.

Centripetal acceleration:

$$a_c = \frac{v^2}{r} \quad (\text{uniform circular motion})$$

- A vector that is always directed towards the center of the circular motion, *i.e.*, it's direction changes constantly.

Newton's 2nd law and uniform circular motion



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Centripetal force:

$$F_c = ma_c = m \frac{v^2}{r} \quad (\text{uniform circular motion})$$

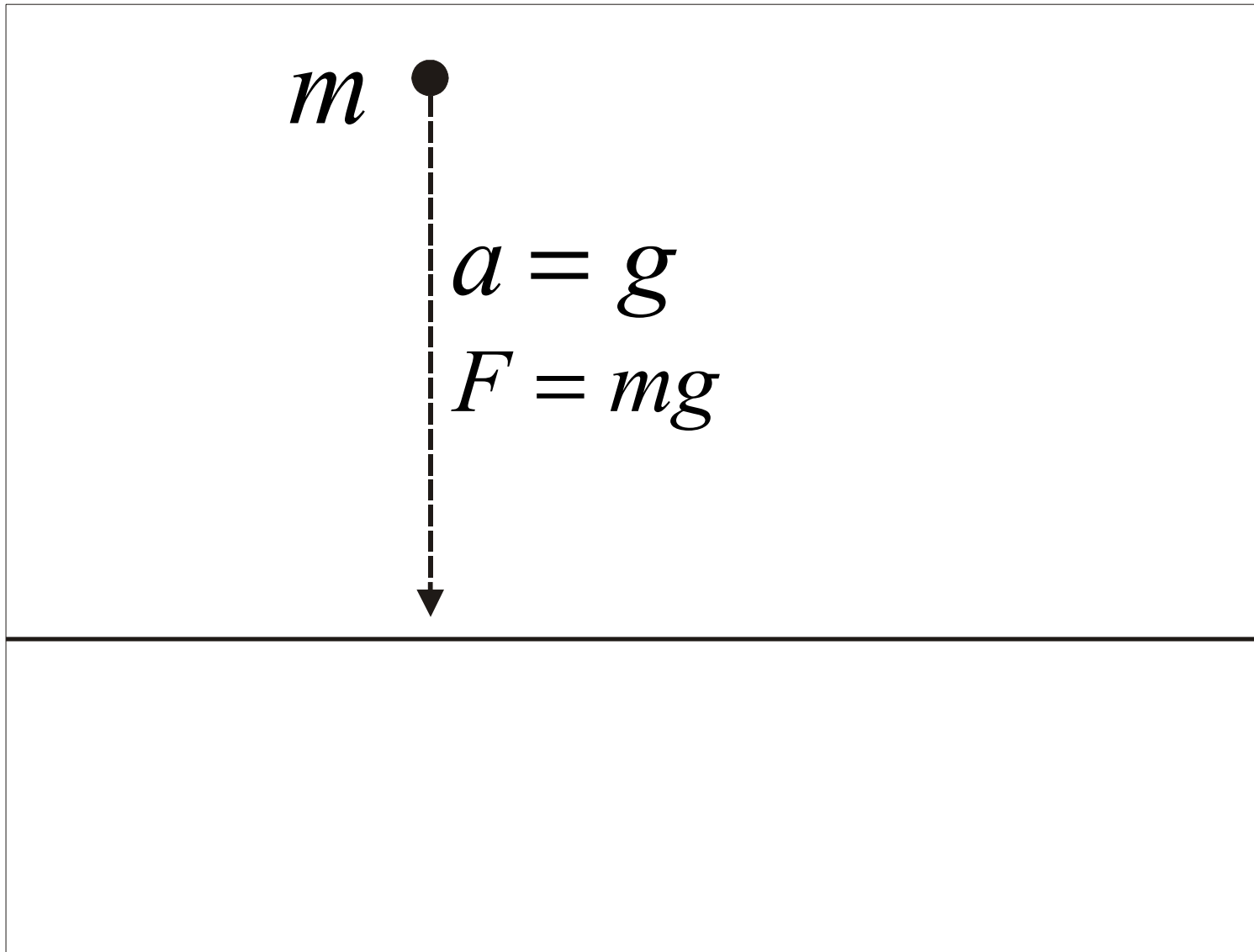
$$\text{Period: } T = \frac{2\pi r}{v} \quad (\text{sec}) \quad \text{Frequency: } f = \frac{1}{T} = \frac{1}{2\pi r} v \quad (\text{sec}^{-1})$$

Newton's 2nd law and uniform circular motion

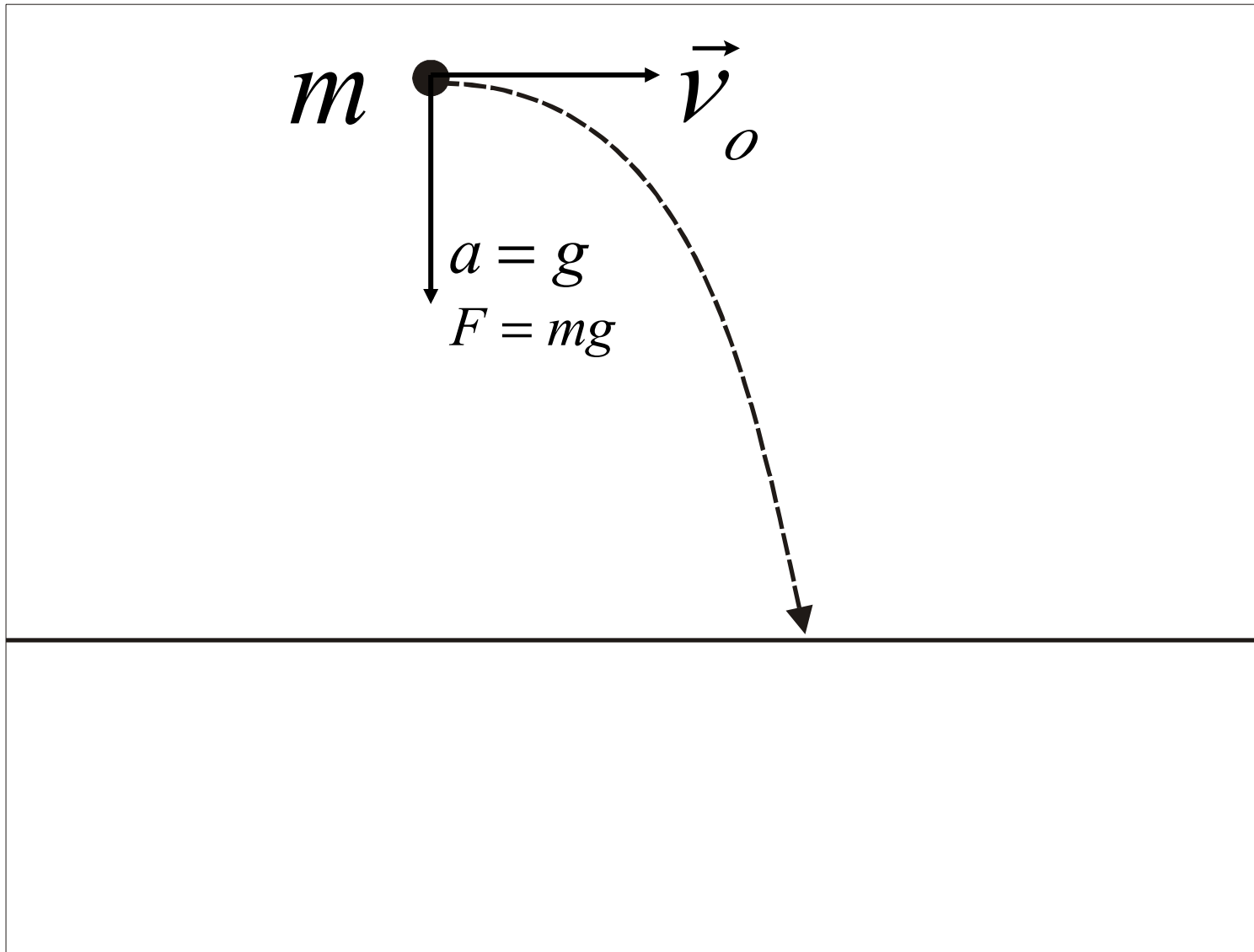
The vectors \vec{a} , \vec{F} , \vec{v} and \vec{r} are constantly changing

- The magnitudes a , F , v and r are constants of the motion.
- The frame in which the mass is moving is not inertial, *i.e.*, it is accelerating.
- Therefore, one cannot apply Newton's laws in the moving frame associated with the mass.
- However, we can apply Newton's laws from the stationary lab frame.
- Examples of centripetal forces: gravity on an orbiting body; the tension in a string when you swirl a mass in around in a circle; friction between a car's tires and the racetrack as a racing car makes a tight turn....

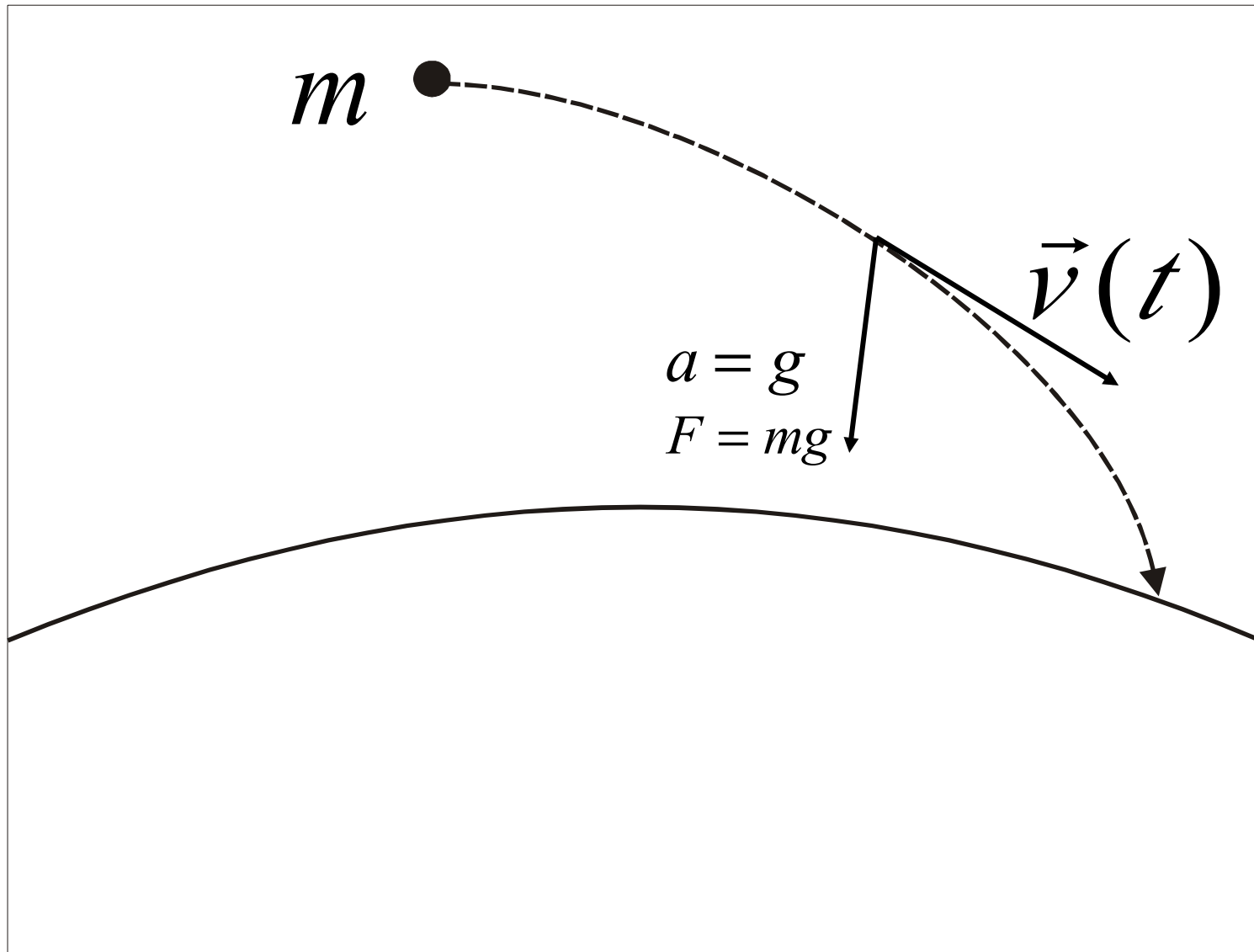
So why do you appear weightless in orbit?



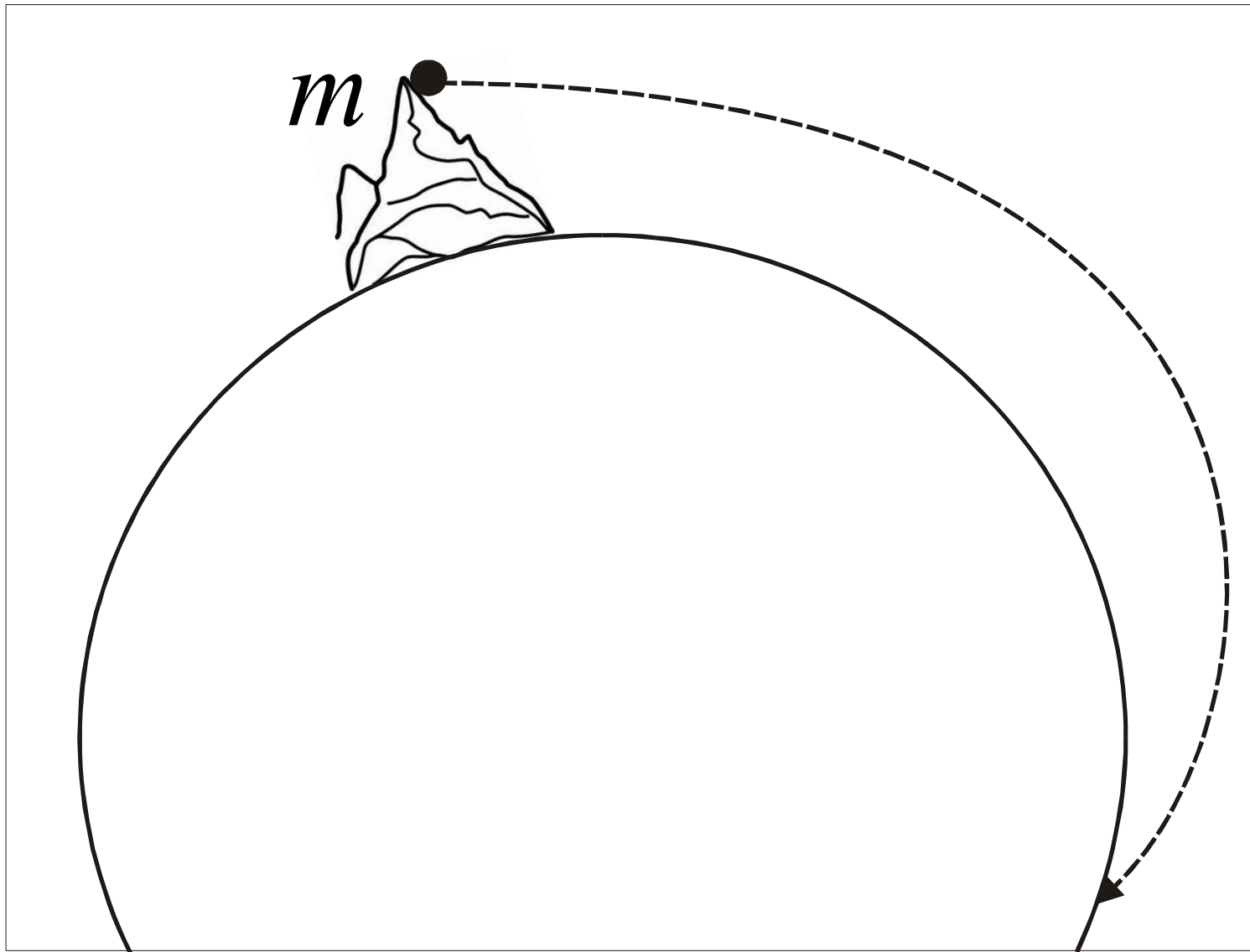
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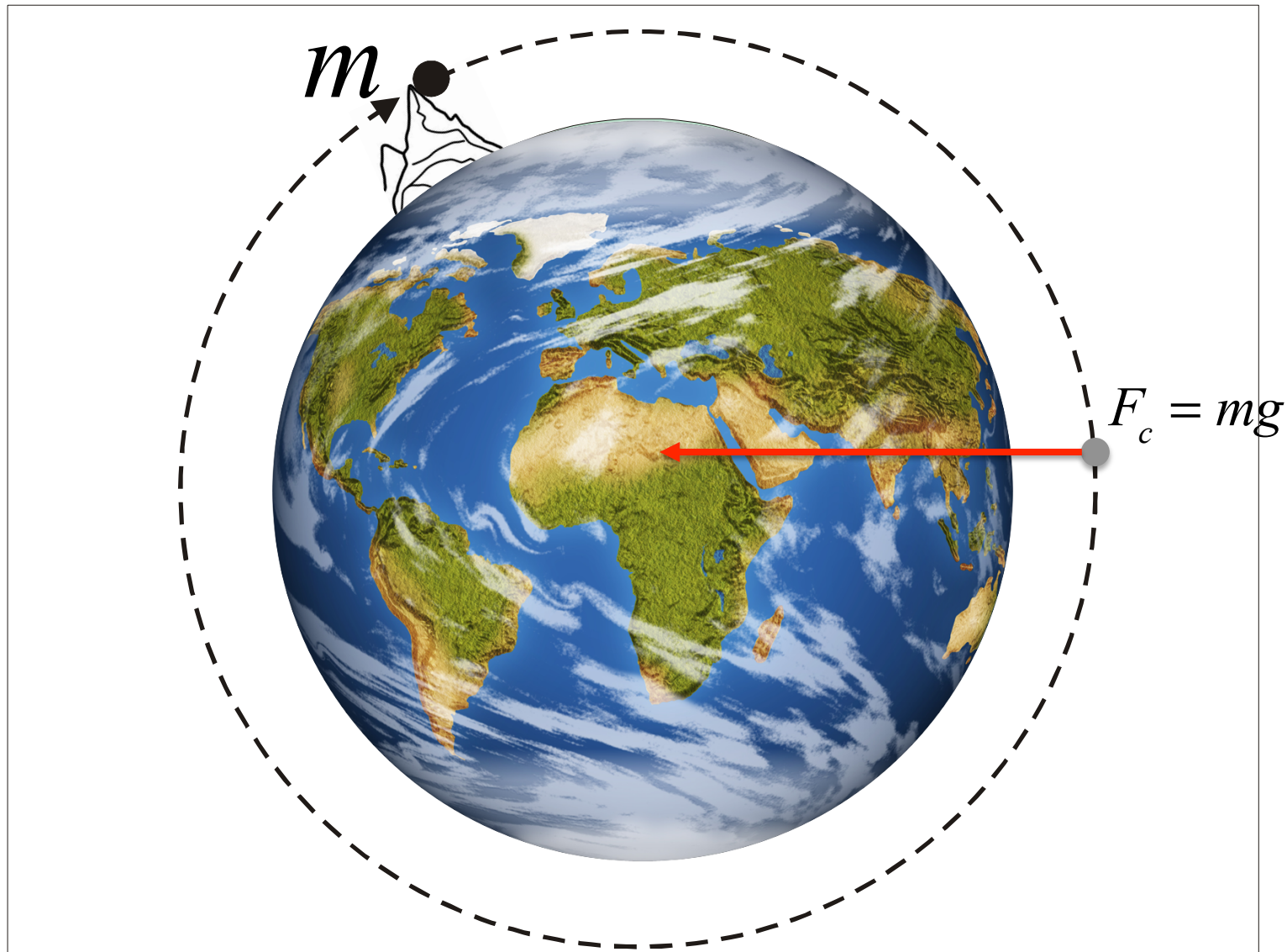
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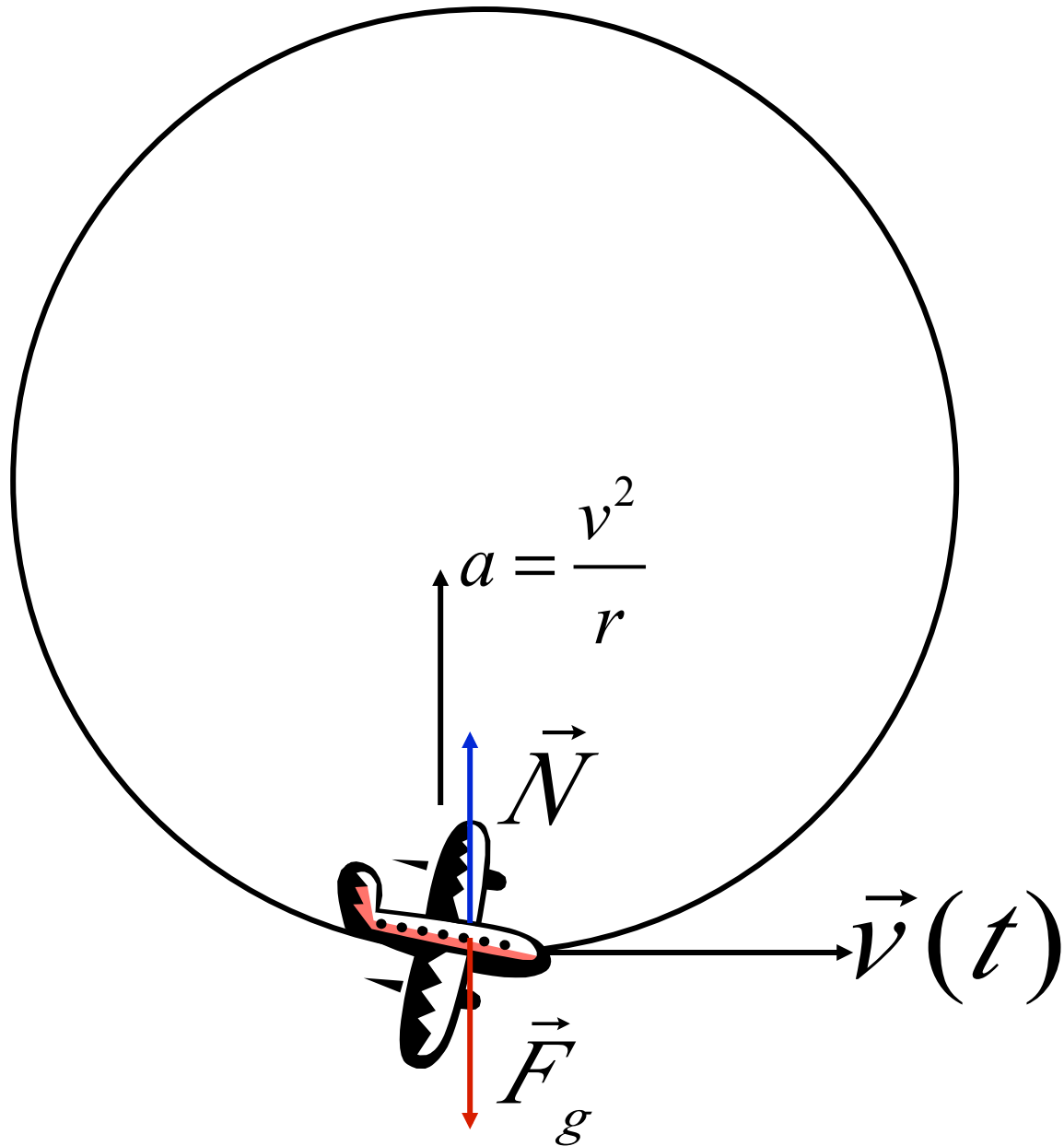


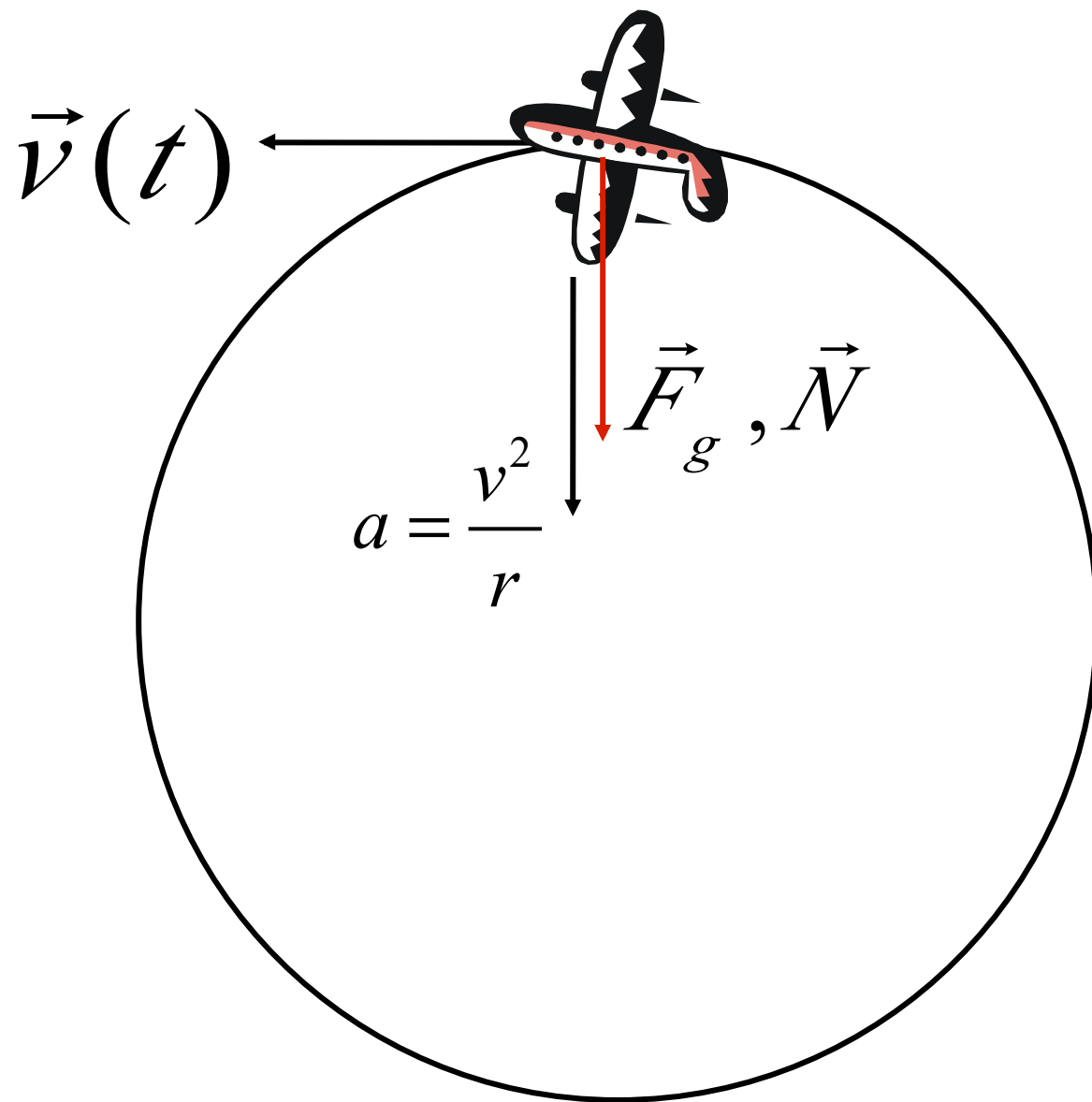
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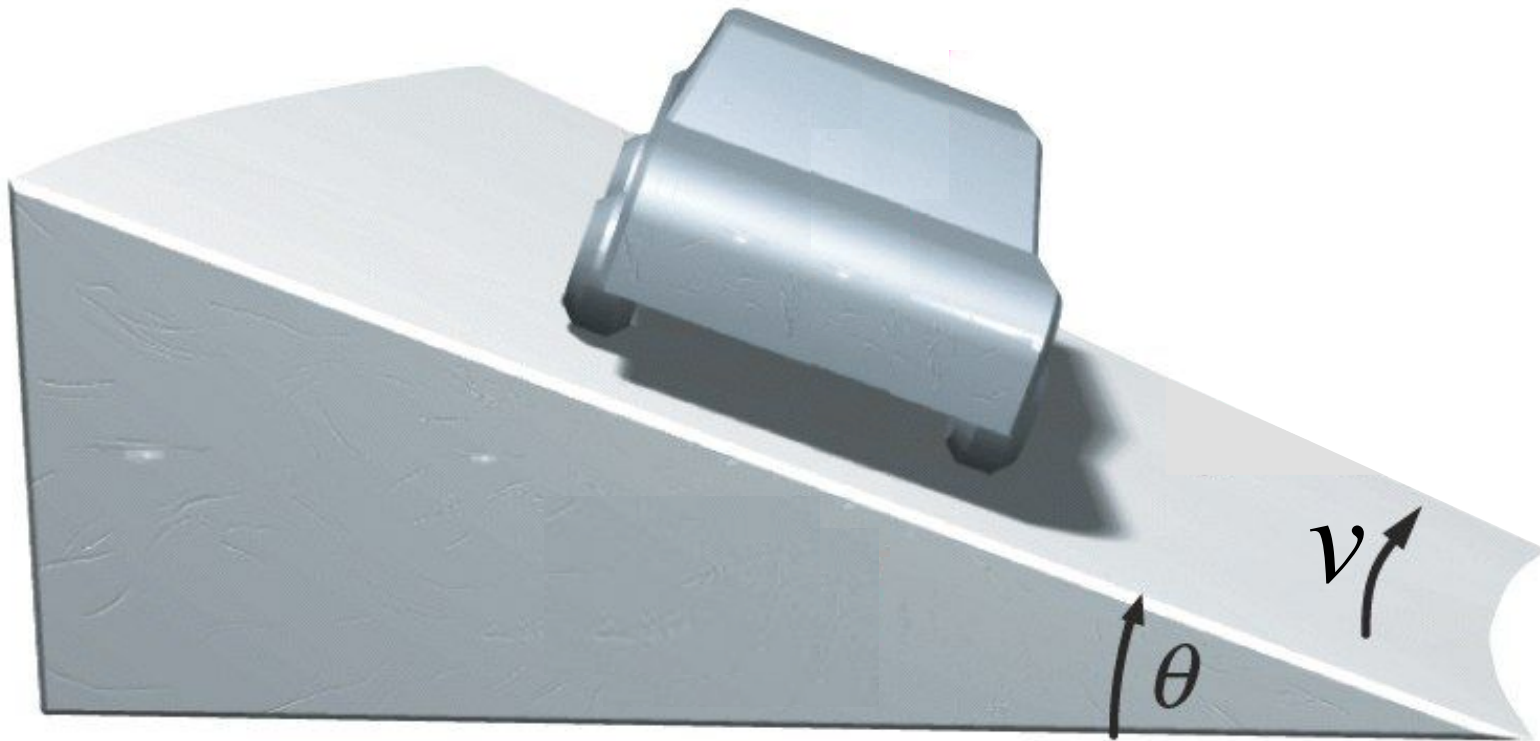
You are in constant free-fall!

Looping the loop

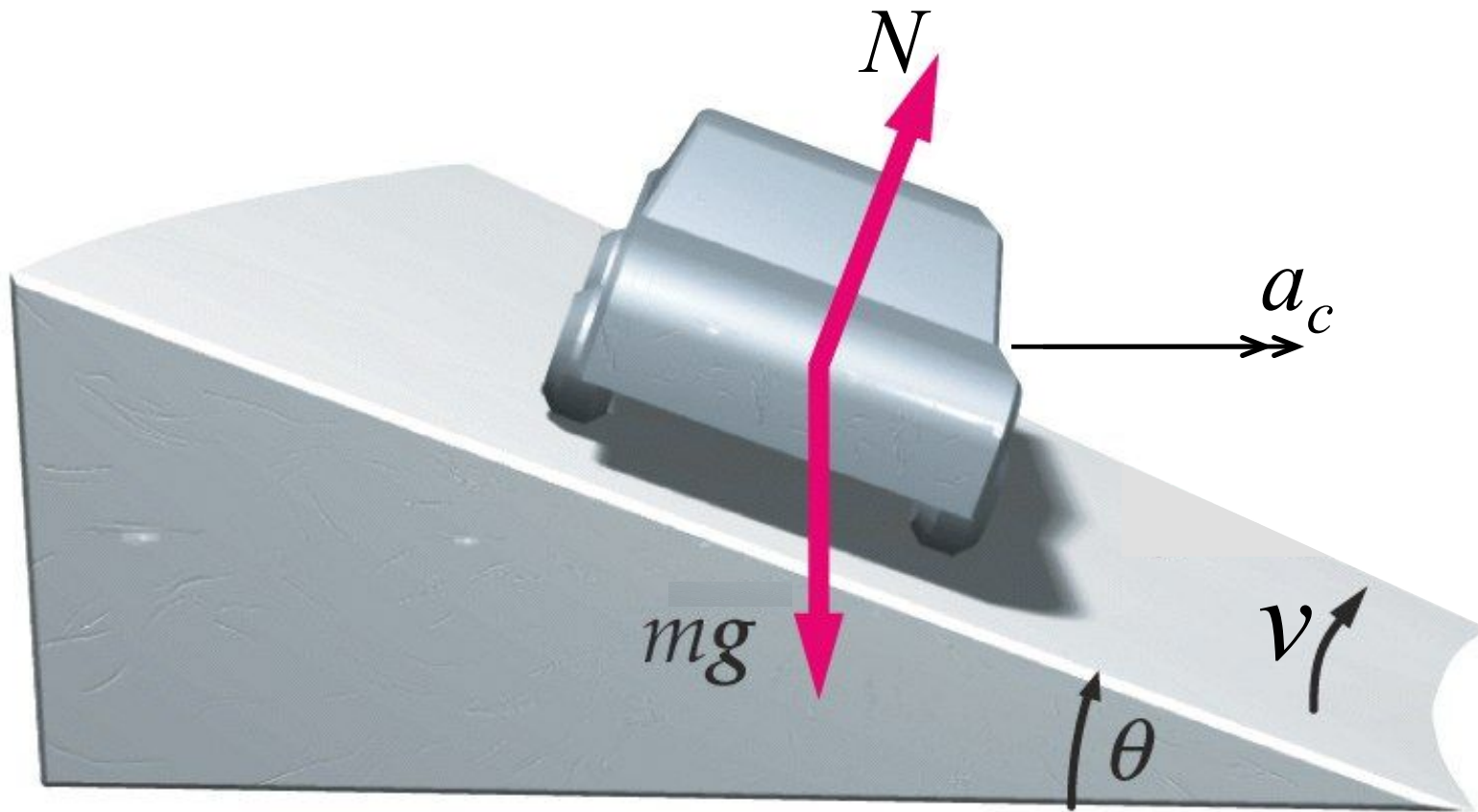




Daytona 500: the racetrack is covered in ice (!), so the physicist cannot rely on friction to prevent him/her from sliding off. How is it that he/she can continue the race?



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Energy

- Energy is a scalar* quantity (a number) that we associate with a system of objects, *e.g.*, planets orbiting a sun, masses attached to springs, electrons bound to nuclei, *etc.*
- Forms of energy: **kinetic**, **chemical**, **nuclear**, **thermal**, **electrostatic**, **gravitational**....
- It turns out that energy possesses a fundamental characteristic which makes it very useful for solving problems in physics: ****Energy is ALWAYS conserved****

Kinetic energy K is energy associated with the state of motion of an object. The faster an object moves, the greater its kinetic energy.

Potential energy U represents stored energy, *e.g.*, in a spring. It can be released later as kinetic energy.

*This can make certain kinds of problem much easier to solve mathematically.

Work - Definition

Work W is the energy transferred to or from an object by means of a force acting on the object. Energy transferred to the object is positive work, and energy transferred from the object is negative work.

- If you accelerate an object to a greater speed by applying a force on the object, you increase its kinetic energy K ; you performed work on the object.
- Similarly, if you decelerate an object, you decrease its kinetic energy; in this situation, the object actually did work on you (equivalent to you doing negative work).

Work - Definition

Work W is the energy transferred to or from an object by means of a force acting on the object. Energy transferred to the object is positive work, and energy transferred from the object is negative work.

- If an object moves in response to your application of a force, you have performed work.
- The further it moves under the influence of your force, the more work you perform.
- There are only two relevant variables in one dimension:
the force, F_x , and the displacement, Δx .

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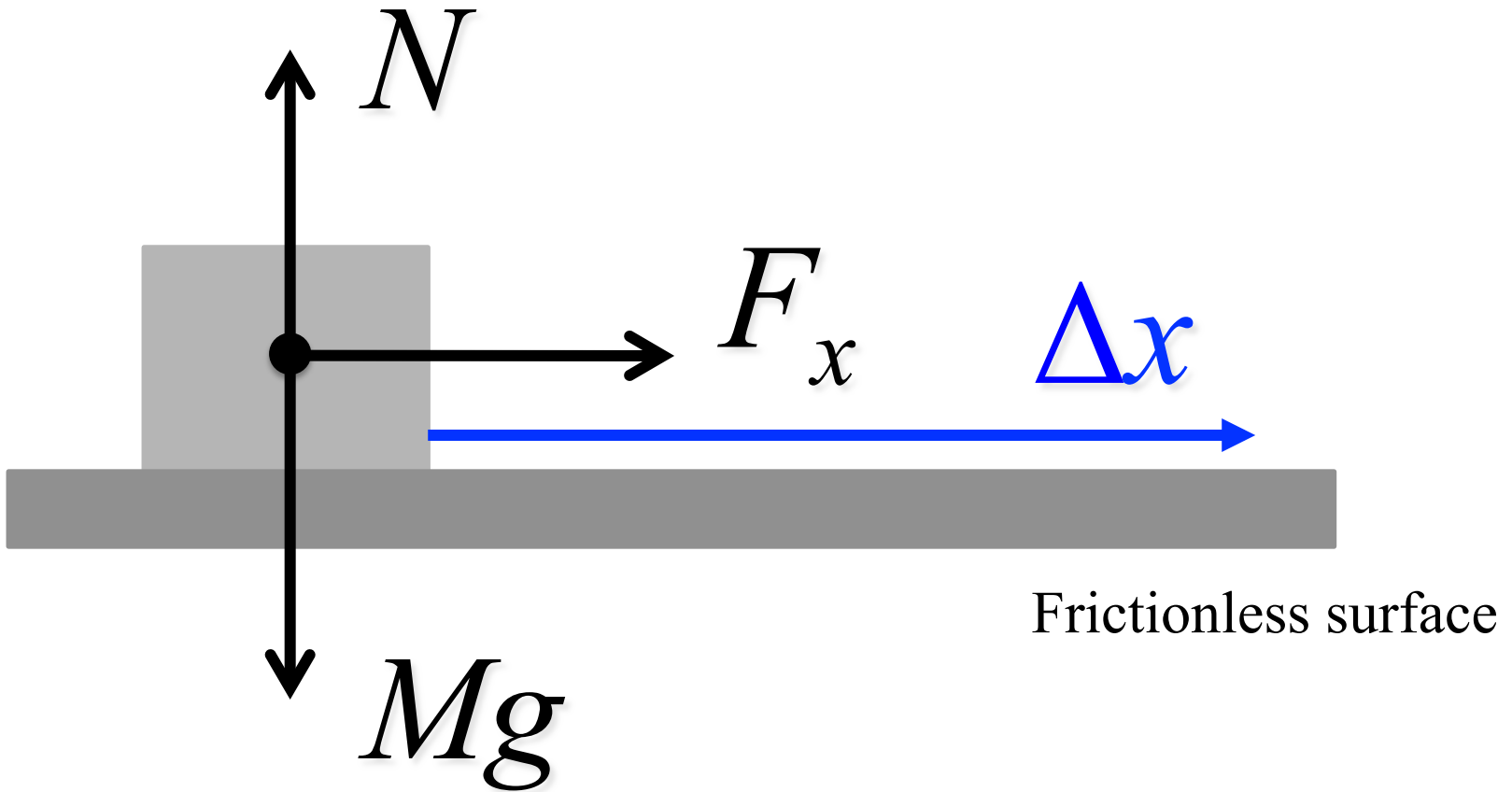
- There are only two relevant variables in one dimension: the force, F_x , and the displacement, Δx .

Definition: $W = F_x \Delta x$ [Units: N.m or Joule (J)]

F_x is the component of the force in the direction of the object's motion, and Δx is its displacement.

- Examples:
 - Pushing furniture across a room;
 - Carrying boxes up to your attic.

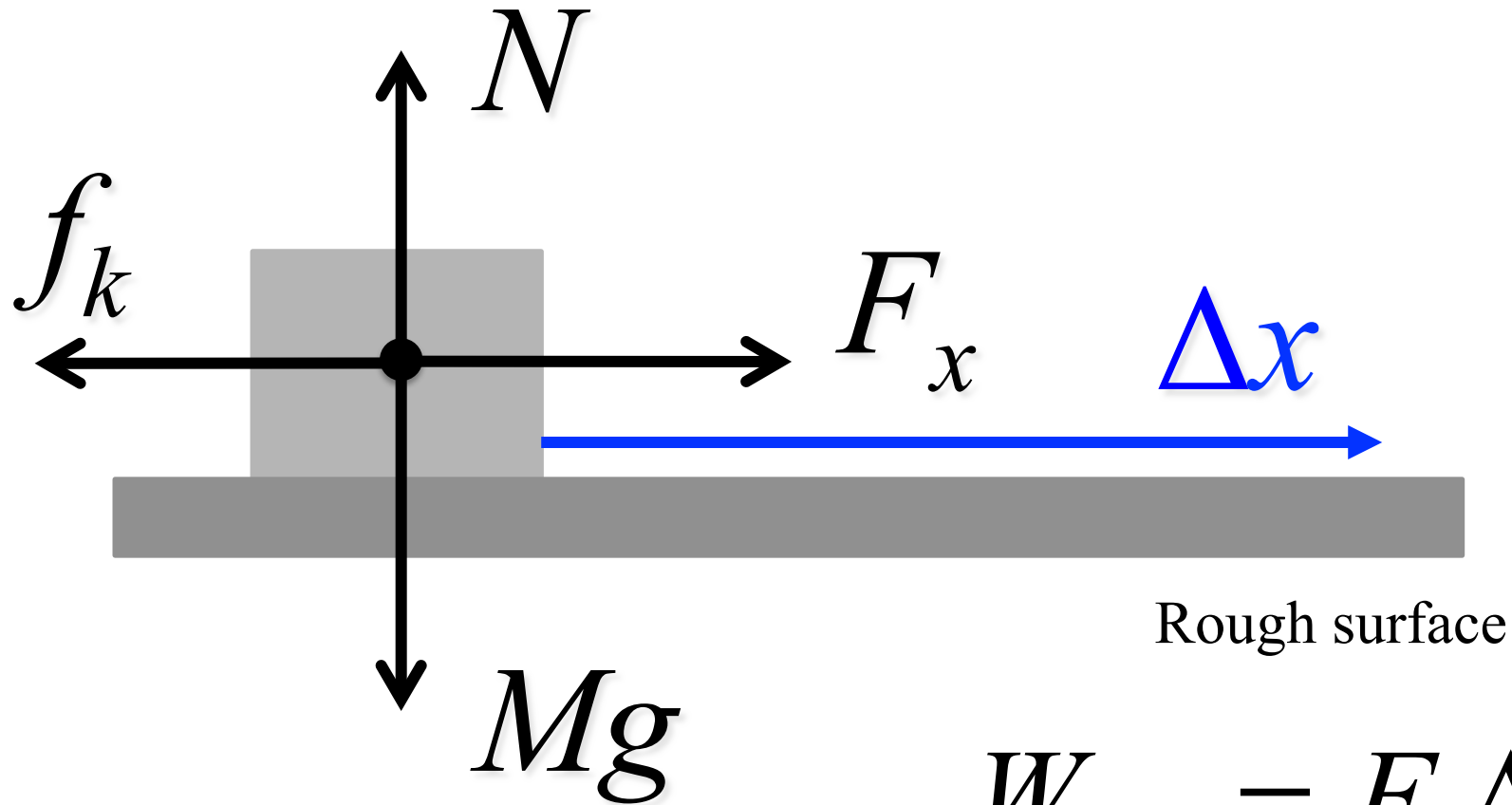
Work - Examples



$$W = F_x \Delta x$$

Work - Examples

These two seemingly similar examples are, in fact, quite different

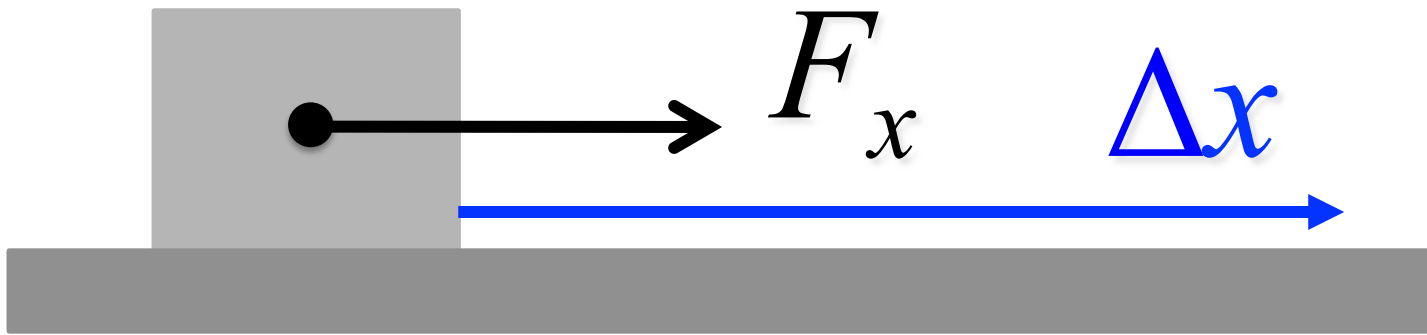


$$W_{\text{Pull}} = F_x \Delta x$$

$$W_{\text{fric.}} = -f_k \Delta x$$

Work - Examples

$$v_f^2 = v_i^2 + 2a_x \Delta x$$



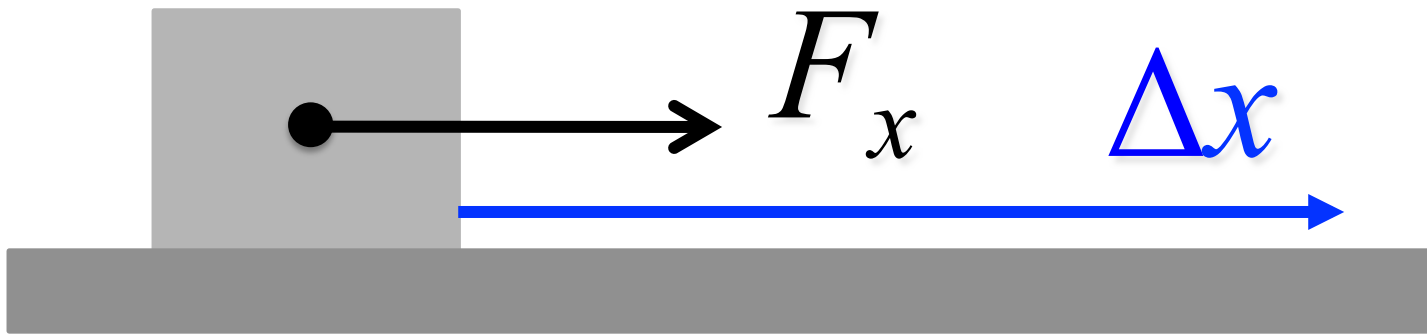
Frictionless surface

$$\frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \frac{1}{2} m \times 2 a_x \Delta x$$

$$\Delta K = K_f - K_i = m a_x \Delta x = F_x \Delta x = W$$

Kinetic Energy - Definition

$$K = \frac{1}{2} m v^2$$



Frictionless surface

$$\frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \frac{1}{2} m \times 2 a_x \Delta x$$

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Work-Kinetic Energy Theorem

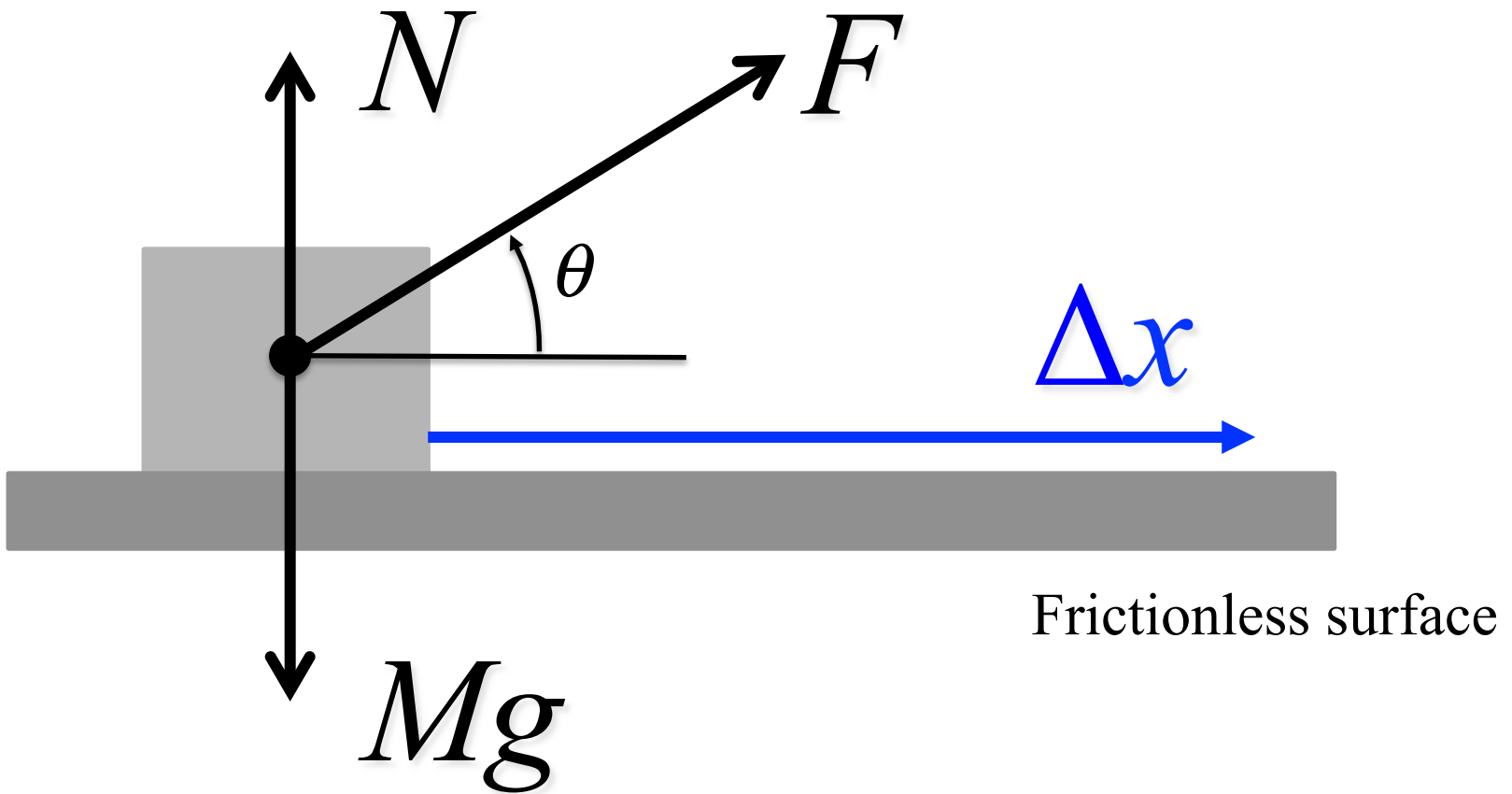
$$\Delta K = K_f - K_i = W_{\text{net}}$$

$$\left(\begin{array}{l} \text{change in the kinetic} \\ \text{energy of a particle} \end{array} \right) = \left(\begin{array}{l} \text{net work done on} \\ \text{the particle} \end{array} \right)$$

$$K_f = K_i + W_{\text{net}}$$

$$\left(\begin{array}{l} \text{kinetic energy after} \\ \text{the net work is done} \end{array} \right) = \left(\begin{array}{l} \text{kinetic energy} \\ \text{before the net work} \end{array} \right) + \left(\begin{array}{l} \text{the net} \\ \text{work done} \end{array} \right)$$

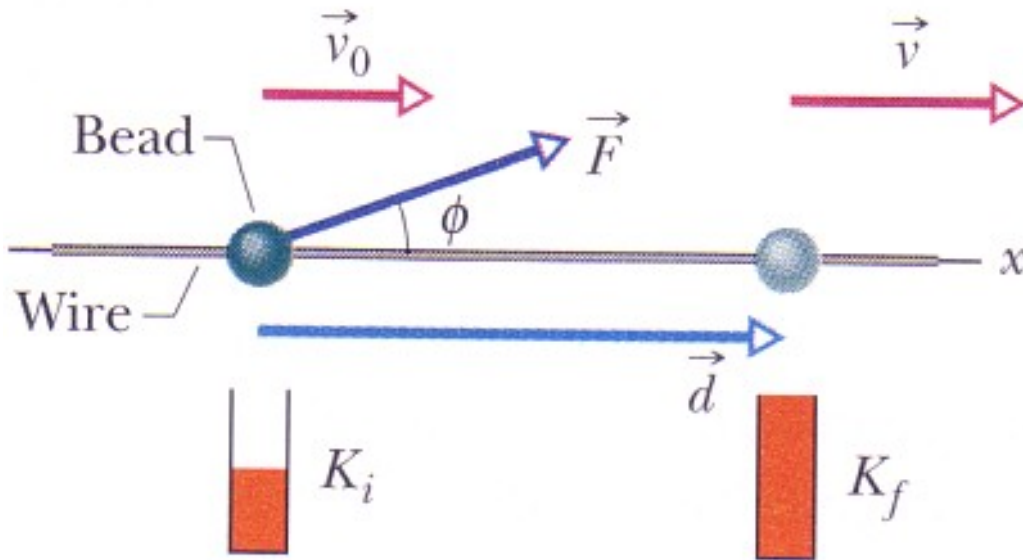
More on Work



$$\begin{aligned} W &= F_x \Delta x \\ &= F \cos \theta \cdot \Delta x \end{aligned}$$

More on Work

To calculate the **work** done on an object by a force during a displacement, we use only the force component along the object's displacement. The force component perpendicular to the displacement does zero work



$$F_x = F \cos \phi$$

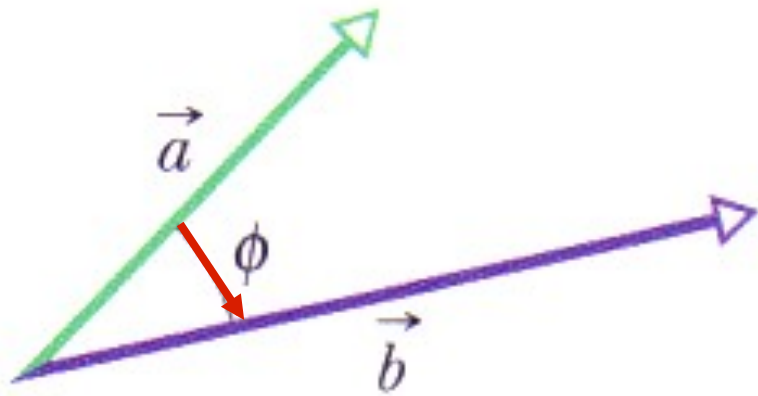
$$W = Fd \cos \phi$$

$$W = \vec{F} \cdot \vec{d}$$

- Caution: for all the equations we have derived so far, the force must be constant, and the object must be rigid.
- I will discuss variable forces later.

The scalar product, or dot product

$$\vec{a} \cdot \vec{b} = ab \cos \phi$$



$$(a)(b \cos \phi) = (a \cos \phi)(b)$$

$$\cos \phi = \cos(-\phi)$$

$$\Rightarrow \vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

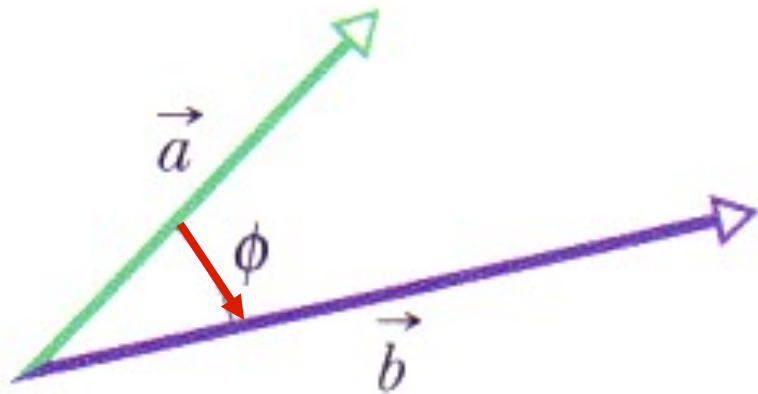
- The scalar product represents the product of the magnitude of one vector and the component of the second vector along the direction of the first

$$\text{If } \phi = 0^\circ, \text{ then } \vec{a} \cdot \vec{b} = ab$$

$$\text{If } \phi = 90^\circ, \text{ then } \vec{a} \cdot \vec{b} = 0$$

The scalar product, or dot product

$$\vec{a} \cdot \vec{b} = ab \cos \phi$$



$$(a)(b \cos \phi) = (a \cos \phi)(b)$$

$$\cos \phi = \cos(-\phi)$$

$$\Rightarrow \vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

- The scalar product becomes relevant in Chapter 6 (pages 88 and 97) when considering work and power.
- There is also a vector product, or cross product, which becomes relevant in Chapter 11 (pages 176-178). I save discussion of this until later in the semester.
- See also Appendix A.